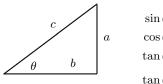
Formula Sheet, Physics 1P21/1P91 \_\_\_\_\_\_ Jan-Apr 2023

## Mathematics

quadratic equation,  $ax^2 + bx + c = 0$ :

$$x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

trigonometry:  $a^2 + b^2 = c^2$ 



$$\sin \theta = a/c$$

$$\cos \theta = b/c$$

$$\tan \theta = a/b$$

$$\tan \theta = \frac{\sin \theta}{\cos \theta}$$

circular arc ( $\theta$  in rad):  $s = \theta r$ for a full circle,  $\theta = 2\pi$  and  $s = 2\pi r$ 

## **Fundamental Constants**

 $g = 9.80 \text{ m·s}^{-2}$   $c = \text{speed of light} = 2.99792458 \times 10^8 \approx 3.00 \times 10^8 \text{ ms}^{-1}$   $m_e = \text{ mass of electron} = 9.11 \times 10^{-31} \text{ kg}$   $m_p = \text{ mass of proton} = 1.6726 \times 10^{-27} \text{ kg}$   $m_n = \text{ mass of neutron} = 1.6749 \times 10^{-27} \text{ kg}$   $G = \text{ gravit. constant} = 6.674 \times 10^{-11} \text{ N·m}^2 \cdot \text{kg}^{-2}$   $R_E = \text{ radius of Earth} = 6.376 \times 10^6 \text{ m}$   $M_E = \text{ mass of Earth} = 5.9736 \times 10^{24} \text{ kg}$   $R_L = \text{ radius of Moon} = 1.74 \times 10^6 \text{ m}$   $M_L = \text{ mass of Moon} = 7.35 \times 10^{22} \text{ kg}$   $T_L = \text{ orbital period} = 2.36 \times 10^6 \text{ s}$   $R_{E-L} = \text{ Earth-Moon distance} = 3.84 \times 10^8 \text{ m}$   $R_S = \text{ radius of Sun} = 6.96 \times 10^8 \text{ m}$   $M_S = \text{ mass of Sun} = 1.99 \times 10^{30} \text{ kg}$   $R_{E-S} = \text{ Earth-Sun distance} = 1.496 \times 10^{11} \text{ m}$ 

## Mechanics

motion in a straight line with a = constant:

$$\begin{array}{rcl} x & = & x_0 + \bar{v}t \longrightarrow \Delta x = \bar{v}t \\ \bar{v} & = & \frac{v_0 + v}{2} \\ v & = & v_0 + at \longrightarrow \Delta v = at \\ \Delta x & = & v_0t + \frac{1}{2}at^2 \\ v^2 & = & v_0^2 + 2a\Delta x \end{array}$$

Relative velocity:  $\vec{\mathbf{v}}_{AC} = \vec{\mathbf{v}}_{AB} + \vec{\mathbf{v}}_{BC}$ Newton's Laws:

$$\begin{array}{ll} \text{N1L:} & \vec{\mathbf{F}}_{\text{net}} = 0 \implies \vec{\mathbf{a}} = 0 \\ \text{N2L:} & \vec{\mathbf{a}} = \frac{1}{m} \vec{\mathbf{F}}_{\text{net}} \longrightarrow \vec{\mathbf{F}}_{\text{net}} = m \vec{\mathbf{a}} \\ \text{N3L:} & \vec{\mathbf{F}}_{\text{A on B}} = -\vec{\mathbf{F}}_{\text{B on A}} \\ \text{Gravity:} & F = G \frac{m \, M}{m^2} \end{array}$$

friction:

$$f_s \leq f_s^{(max)} = \mu_s N$$
  
 $f_k = \text{const} = \mu_k N, \quad \mu_k < \mu_s$ 

kinematics of circular motion with  $\alpha = \text{constant}$ :

$$\theta = \theta_0 + \bar{\omega}t \longrightarrow \Delta\theta = \bar{\omega}t$$

$$\bar{\omega} = \frac{\omega_0 + \omega}{2}$$

$$\omega = \omega_0 + \alpha t \longrightarrow \Delta\omega = \alpha t$$

$$\Delta\theta = \omega_0 t + \frac{1}{2}\alpha t^2$$

$$\omega^2 = \omega_0^2 + 2\alpha\Delta\theta$$

rolling without slipping:  $\Delta s = r\Delta\theta$ ,  $v_T = r\omega$ ,  $a_T = r\alpha$  centripetal force and acceleration (for  $\alpha = 0$ ):

$$F_c = ma_c = m \frac{v_T^2}{r} = mr\omega^2$$

torque  $\tau = \text{force} \times \text{lever arm} = Fr_{\perp} = rF \sin \theta$ moment of inertia:  $I = mr^2$ about an axis through the geometrical centre:

$$\begin{split} I_{\rm hoop} &= mr^2 \quad I_{\rm disk} = \frac{1}{2}\,mr^2 \quad I_{\rm rod} = \frac{1}{12}\,mL^2 \\ I_{\rm sphere} &= \frac{2}{5}\,mr^2 \quad I_{\rm sph.shell} = \frac{2}{3}\,mr^2 \end{split}$$

N2L for rotations:  $\tau = I\alpha$  work  $W = Fd\cos\theta$ , or  $W = \tau\,\Delta\theta$  work done by a conservative force:  $W_{\rm c.f.} = -\Delta U$  gravitational potential energy

$$F_{\text{gravity}} = -mg \implies U_g = mgy$$

kinetic energy of translation:  $K = \frac{1}{2} mv^2$ kinetic energy of rotation:  $K = \frac{1}{2} I\omega^2$  conservation of total mechanical energy

$$\Delta U + \Delta K = W_{\text{non-c.f.}}$$

power = rate of doing work =  $W/\Delta t = Fv$  or =  $\tau\omega$  1 Watt = 1 J/s and 1 h.p. = 746 W linear momentum  $\vec{\mathbf{p}} = m\vec{\mathbf{v}}$ 

Impulse =  $\overline{\vec{\mathbf{F}}} \Delta t = \Delta \vec{\mathbf{p}}$ 

conservation of momentum for a system as a whole:

$$\sum \vec{\mathbf{F}}_{\mathrm{ext}} = 0 \implies \vec{\mathbf{p}}_{\mathrm{total}} = \mathrm{const}$$

angular momentum  $\vec{\mathbf{L}} = I\vec{\omega}$ , and  $\bar{\vec{\tau}} = \frac{\Delta\vec{\mathbf{L}}}{\Delta t}$ 

conservation of angular momentum:

$$\vec{\tau}_{\text{net}} = 0 \implies \vec{\mathbf{L}}_{\text{total}} = \text{const} \implies I_1 \omega_1 = I_2 \omega_2$$

## Waves and Sound

simple harmonic oscillator, F = -kx,  $U = \frac{1}{2}kx^2$ 

$$f = 1/T \quad \omega = 2\pi f = \sqrt{k/m}$$
 
$$\begin{cases} x = A\cos\theta = A\cos\omega t \\ v = -A\omega\sin\omega t \\ a = -A\omega^2\cos\omega t \end{cases}$$

travelling wave  $y = A \cos \left( \omega t \mp \frac{2\pi}{\lambda} x \right)$  with  $v = \lambda/T = \lambda f$  string of mass m, length  $\ell$ , volume density  $\rho$ :

$$v_{\mathrm{string}} = \sqrt{\frac{F}{(m/\ell)}} = \sqrt{\frac{F}{(\rho A)}}$$

intensity level:  $\beta=10~\log\left(\frac{I}{I_0}\right)$  dB,  $I_0=1\times 10^{-12}~\mathrm{W/m^2}$  point source intensity:  $I=\frac{P}{A}=\frac{P}{4\pi r^2}$ 

Doppler (upper sign = approach, lower = recede)

$$f = f_s \left( \frac{1 \pm \frac{v_o}{v}}{1 \mp \frac{v_s}{v}} \right)$$
  $v = \text{speed of sound}$   $v_s = \text{speed of source}$   $v_o = \text{speed of observer}$